

DOUBLE EAGLE MINE DISPOSAL VEHICLE









HIGH PRECISION DISPOSAL

Effective detection, classification and identification of a mine threat is crucial to gaining complete situational awareness during underwater operations. An undetected mine remains a danger to forces, so they need sophisticated equipment capable of identifying threats. As a global leader in maritime technology, Saab produces innovative, effective and reliable underwater vehicles.

Saab's Double Eagle MkII Mine Disposal System (Double Eagle MDS) provides a perfect example of Saab's *thinking edge* in action.

Modern mine identification and disposal demands a multifunctional vehicle capable of handling harsh environments with high currents and turbid waters. The top choice for many navies around the world when it comes to mine countermeasures (MCM), the Double Eagle MDS is remotely operated, extending forces' capabilities and helping them stay ahead. The system removes the need for personnel in the water, enabling safer, faster and more efficient MCM operations. The system can be packed into a standard container meaning it can be easily lifted from ship to ship, or be transported by road or air. This efficient stowage capability means that the Double Eagle MDS can quickly go where it is needed.

When ready to use, the system can be launched from any type of ship, from the shore, or from a craft of opportunity (COOP).

OPERATIONAL CONCEPT

When an object has been detected and classified as a Mine-Like Object (MLO) by a ship's mine hunting system, e.g. a hull-mounted sonar, Propelled Variable Depth Sonar (PVDS) or offboard system, the Double Eagle MDS is launched under full control of an onboard operator. The vehicle can then be manually piloted or steered by the autopilot to the vicinity of the MLO. The relocation sonar on the vehicle assists the pilot during this process. When the vehicle is close to the MLO, the pilot manoeuvers it to a position where a positive identification can be made.

Once the target has been confirmed as a mine, the Double Eagle MDS is moved into the optimal position to release the mine disposal charge of choice. Several weapon alternatives are available. When the vehicle has returned to the ship and has been recovered, the charge is remotely detonated and the mine is exploded.

When not used for mine disposal operations, the system can be reconfigured with manipulator arms or other tools for general purpose underwater work.



ARCERS

SANE

BRUSHLESS MOTORS

The thrusters emit very ow electric, magnetic and hydroacoustic noise



MINE RELOCATION SONAR

o a a

The multibeam sonar is used to relocate detected objects



NAVIGATION

USBL, MEMS, DVL and speed log for navigation

DETECT EVERY THREAT

SYSTEM OVERVIEW

vehicle, including an Operator Control Board (OCB), a Portable Operator Control Board (POCB) and software that is ready to run on any general purpose or dedicated vehicle console. The heart of the control system is the Surface Control Unit

and interfaces with all other ship systems. a tether. As well as providing vehicle power and control signals, the tether continuously sends real-time sonar

The Automatic Tension Control (ATC) winch and tether allow the of the tether entangling with other underwater ship systems. They also provide additional stability to the vehicle when decoupling the ship's movements from the vehicle.

The Double Eagle MDS has a Power Converter Unit (PCU) which converts the ship's power to vehicle power. The PCU also includes insulation monitoring with a circuit breaker for added safety. The system features a cradle or trolley for vehicle stowage and a Launch and Recovery System (LARS) for the vehicle. These tools are used in conjunction with a sea crane on board the ship, enabling

The relocation sonar is carried in the bow of the vehicle together with a camera on a tilt table, which allows the sonar and camera to be angled downwards for optimal identification performance.

SYSTEM SPECIFICATIONS

LENGTH	2.2 m
WIDTH	1.3 m
HEIGHT	0.5 m
WEIGHT IN AIR	360 kg
WEIGHT IN WATER	Adjustable, slightly buoyant
SPEED	0–6 knots
OPERATIONAL DEPTH	500 m
PAYLOAD	250 kg
VEHICLE CONTROL	6 Degrees of Freedom, auto depth, auto heading, auto altitude, waypoint steering and autopilot

NAVIGATION Ultra Short Base SENSORS Line (USBL), Microelectromechanical Systems (MEMS), Doppler Velocity Log (DVL) and speed log **Optional:** Inertial Navigation System (INS) and GPS CAMERA Colour camera on tilt table Other types of camera available on request TETHER 1,000 m, 11 mm power and fibre optic POWER SUPPLY Via the tether

COMMUNICATION

Fibre optic -Gigabit, Ethernet

Multibeam forward looking relocation sonar mounted on tilt table Other types of sonar available on request

SONAR ALTERNATIVES



SAAB DEVELOPS HIGH TECHNOLOGY UNDERWATER SYSTEMS THAT ENABLE RCES TO ENHANCE THEIR ARME DF ESS, L S NA MΔ REI -NI) *HEIR OPERATIONAL* T CAPA B S ΊA ND RF \backslash $\supset ($ IN THE HARSH 71/1 EST ENVIRO 5.

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